

# Automated Coregistration of MEG Using Cortical Constraints

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Intramural Research Program  
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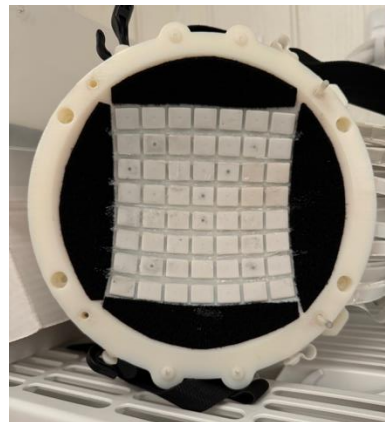
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# Why is it Necessary to Refine Coregistration?

- Development of MagnetoCorticoGraph (MCoG) for non-invasive cortical mapping
- OPMs can record high spatial frequencies
- Source solution resolution can be improved by using cortical normal vectors
- Present coregistration methods are not sufficiently accurate for using normal
- Available coregistration methods using **external** features include:
  - head coils & MRI markers
  - images of head, markers, and MRI (e.g., BrainSight™)
- ***These methods do not account for postural changes in brain position***

- We introduce coregistration using the MEG data with **internal** (cortical) anatomy



56 primary sensors  
In 7x8 array  
+ 3 references

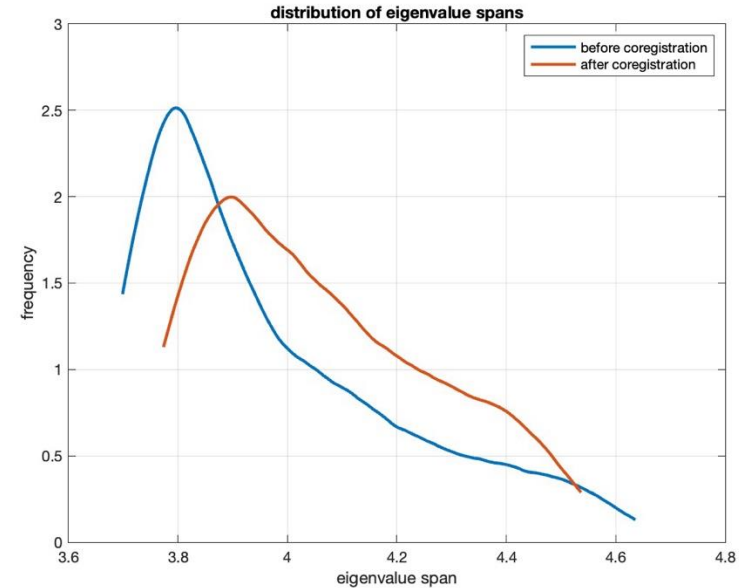


subject with sensor  
array placed over  
left sensorimotor  
cortex

# Principle: alignment of cortical images derived from constrained & unconstrained moment vectors

- Coregistration is based upon comparison of the anatomical cortical normal vectors (**constrained** moment vector) with that (**unconstrained** moment vector) computed from the MEG data using an eigensystem solution
- The reliability of the MEG moment vector estimates are related to the span of the eigenvalues of the eigensystem solution:

$$\mathbf{L}_r^T \mathbf{C}^{-2} \mathbf{L}_r \mathbf{e}_k = \lambda_k \mathbf{L}_r^T \mathbf{C}^{-1} \mathbf{L}_r \mathbf{e}_k, \text{ where } \mathbf{C} = \mathbf{E}[\mathbf{M}\mathbf{M}^T]$$



# Principle (cont'd): cortical image alignment

- Comparison of constrained & unconstrained moment vectors are ambiguous in  $2\pi$
- Instead, derive cortical surface images using:

$$b_{\text{constrained}} = \|\mathbf{L}_r \mathbf{u}_{\text{vertex}}\|$$
$$b_{\text{unconstrained}} = \|\mathbf{L}_r \mathbf{e}_{\text{min}}\|$$

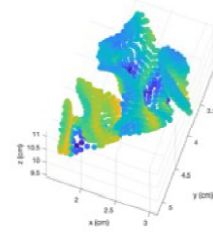
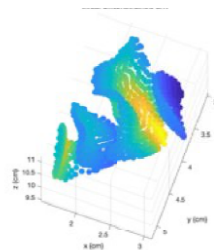
- Iteratively coregister the MEG & MRI by transforming the sensor array position & orientation so that the unconstrained and constrained vertices are maximally correlated

cortical surface forward solutions  
under MCoG array

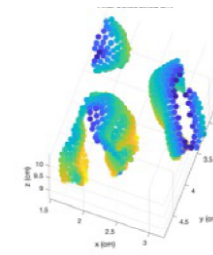
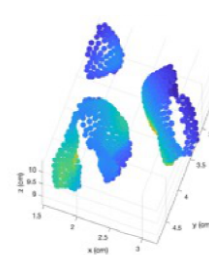
*unconstrained*

*constrained*

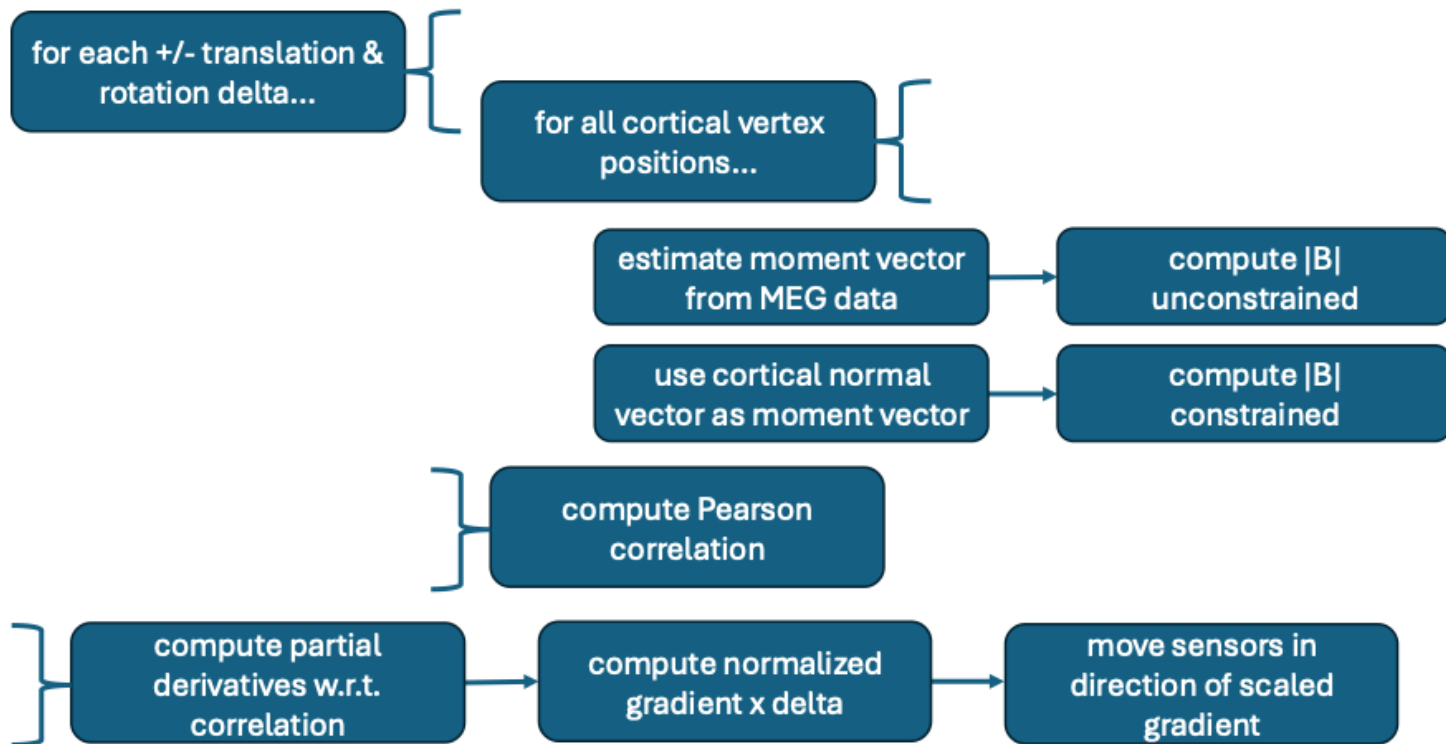
*Before  
Coregistration  
R=-0.085*



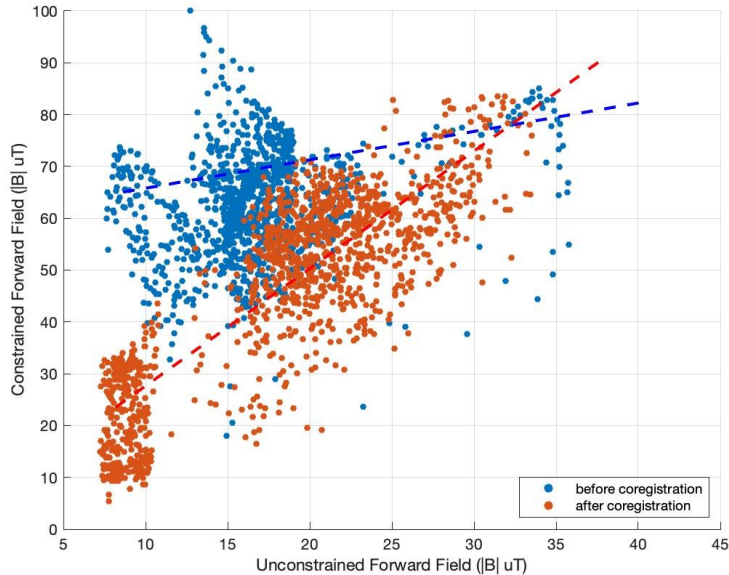
*After  
Coregistration  
R=0.564*



# Flow Diagram for Each Iteration



# SEF Subject – Pial Surface Scattergram



Results after 500 iterations:

**x (mm) y (mm) z (mm)  $\theta$  (deg)  $\phi$  (deg)**

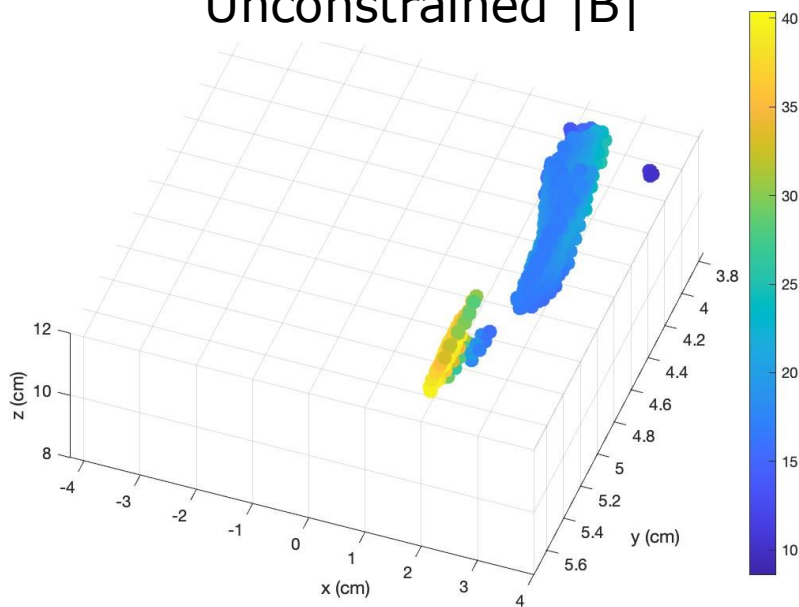
**0.714 5.553 2.817 0.313 -0.870**

Initial correlation: **0.246** for 1162 vertices

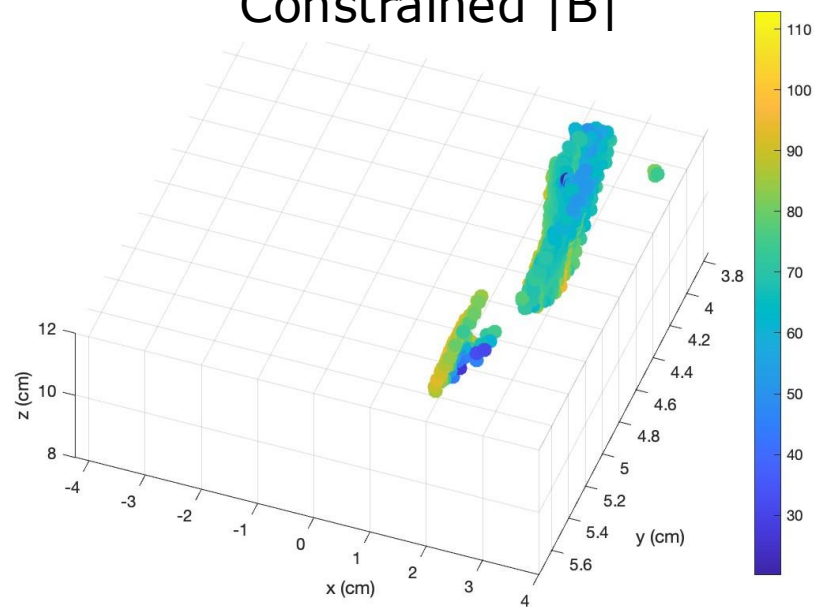
Final correlation: **0.841** for 1279 vertices

# Before Coregistration: forward solution map for 1000+ vertices with the largest eigenvalue span

Unconstrained  $|B|$

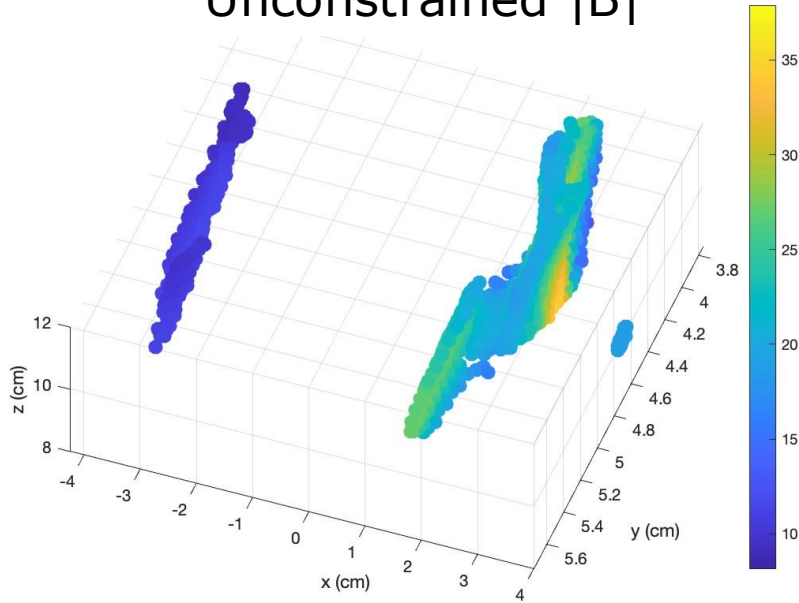


Constrained  $|B|$

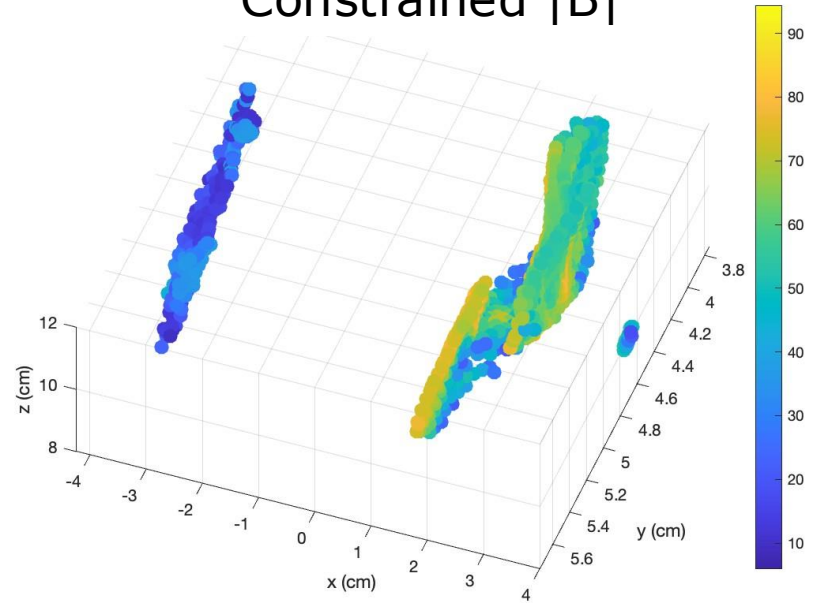


# After Coregistration: forward solution map for 1000+ vertices with the largest eigenvalue span

Unconstrained  $|B|$

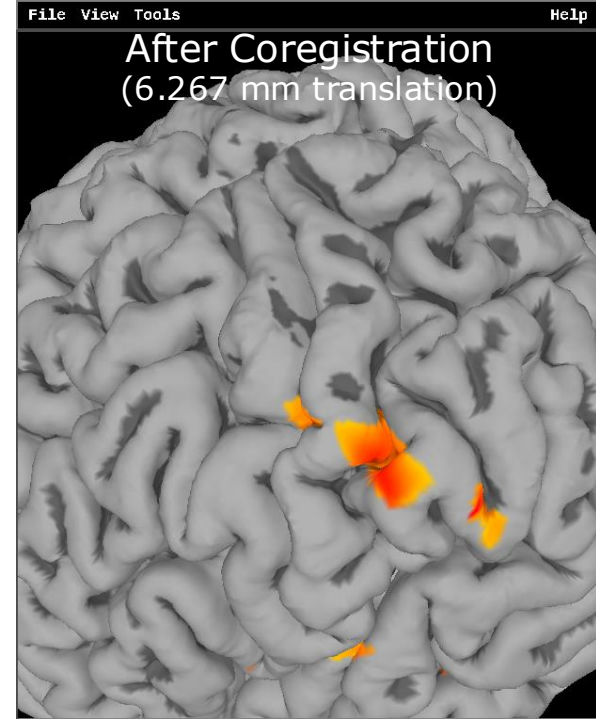
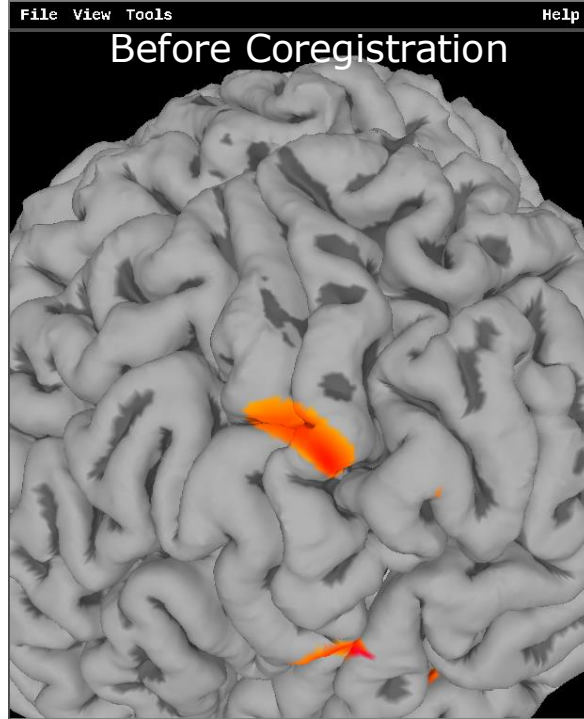


Constrained  $|B|$





# SEF Subject – Beta Band ERD



# Prerequisites & Limitations

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- Requirements:

- † Sensor array must be calibrated for position, sensing vector, gain, & crosstalk
  - MRI must be free of geometric distortion
  - MRI segmentation must be high quality
  - MEG data must be free of sensor movement with respect to the head

† Presented in Symposium: Localization accuracy of OPM MEG, Wednesday 28<sup>th</sup>  
10:06 - 11:27

- Grossly underdetermined problem – up to 250,000 vertices & 56 sensors
- Selection of surface – pial or smooth white matter
- Selection of number of significant vertices
- Frequency bandpass
- Interaction between translation & rotation
- Minimum eigenvalue span (reliability of unconstrained moment vector estimate)
- Minimum number of vertices used
- Cortical normal vector range used
- Dependency on cortical activity? (tbd)



# *OPM Team at the NIMH MEG Core Facility*

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Stephen Robinson***



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[irp.nih.gov](http://irp.nih.gov)

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